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A UNIFIED APPROACH TO POWER SYSTEM SENSITIVITY ANALYSIS AND PLANNING

PART II: SPECIAL CLASS OF ADJOINT SYSTEMS

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# A UNIFIED APPROACH TO POWER SYSTEM SENSITIVITY ANALYSIS AND PLANNING

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### Abstract

A unified approach to power system sensitivity analysis and planning has been presented in a companion paper, where a family of adjoint systems based on the exact a.c. power flow model was described. Here, we consider a class of this family in which the extended Tellegen sum is a real quantity. An important practical case is discussed in which the adjoining complex coefficients are set to particular values, which result in an adjoint system of a special structure. The adjoint matrix of coefficients is shown to be of the same size and sparsity as the Jacobian matrix of the original power network. The required sensitivity expressions are derived and tabulated for direct use in sensitivity analysis and gradient evaluation and are common to all relevant power system studies. Numerical examples are presented based on a 6-bus sample power system.

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## I. INTRODUCTION

In power system studies such as optimal power flow, contingency analysis and planning [1] the sensitivities of the system states and the derivatives of objective functions and constraints w.r.t. the control variables are required to be calculated in an efficient way. The adjoint network approaches to these problems, which are based on the exact a.c. power flow model [2,3] appear to be superior to the Lagrange multiplier method [4] since they afford a great deal of dimensionality reduction and scheme compactness. A unified approach to power system sensitivity analysis and planning exploiting the adjoint network concept has been presented in Part I of this paper [5]. A family of adjoint systems based on the exact a.c. power flow model has been fully described. In this part, namely Part II, we consider a class of this family in which the extended Tellegen sum is a real quantity.

We discuss in detail an important practical case in which the adjoining complex coefficients are set to particular values which result in an adjoint system of a special structure. The transmission line admittances of both the original and the adjoint systems turn out to be identical. The required sensitivity expressions for this special case are derived and tabulated for direct use in sensitivity analysis and gradient evaluation. These sensitivity expressions are common to all relevant power system studies.

Numerical examples are presented for a 6-bus sample power system. The sensitivities and gradient vectors of several types of functions are considered for the purpose of illustration and comparison.

## II. REAL EXTENDED TELLEGEN SUM

Equation (7) of Part I describes the general form of the extended Tellegen sum. To obtain a real extended Tellegen sum, it is sufficient for the adjoining complex coefficients to satisfy the conditions

$$\bar{\alpha} = \alpha^*, \bar{\beta} = \beta^*, \bar{\xi} = \xi^*, \bar{\nu} = \nu^* \quad (1a)$$

and

$$\bar{\Gamma}_k = \Gamma_k^* \text{ for all } k. \quad (1b)$$

Hence, the extended Tellegen sum is written as

$$\begin{aligned} \sum_b [\alpha \hat{I}_b V_b + \alpha^* \hat{I}_b^* V_b^* - \beta \hat{V}_b I_b - \beta^* \hat{V}_b^* I_b^* + \xi \hat{I}_b V_b + \xi^* \hat{I}_b^* V_b^* \\ - \nu \hat{V}_b I_b - \nu^* \hat{V}_b^* I_b^* + \sum_k \Gamma_k \lambda_{bk} C_b^k + \sum_k \Gamma_k^* \lambda_{bk} C_b^{k*}] = 0. \end{aligned} \quad (2)$$

Expressing (2) in terms of first-order changes in  $V$  and  $I$ , the resulting perturbed sum is also a real quantity and equations (39) of Part I are consistent for all values of  $\alpha$ ,  $\beta$ ,  $\xi$ ,  $\nu$  and  $\Gamma_k$ .

Equation (2) describes a class of adjoint networks corresponding to different values of the arbitrary complex coefficients  $\alpha$ ,  $\beta$ ,  $\xi$ ,  $\nu$  and  $\Gamma_k$ .

## III. AN IMPORTANT SPECIAL CASE

We consider the special case

$$\alpha = \beta = 1 + j0, \quad (3a)$$

$$\xi = \nu = 0 + j0, \quad (3b)$$

and

$$\Gamma_k = 0 + j0 \text{ for all } k, \quad (3c)$$

which, as we shall see, provides a special structure of the adjoint network. The transmission admittances of both original and adjoint systems are identical. The required gradients in power system sensitivity analysis and planning studies are supplied via one adjoint network analysis.

The matrices  $\Lambda_i^b$ ,  $\bar{\Lambda}_i$ ,  $\Lambda_v^b$  and  $\bar{\Lambda}_v$  of (33) of Part I are given by

$$\Lambda_i^b = \Lambda_i = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}, \quad (4a)$$

$$\bar{\Lambda}_i = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad (4b)$$

$$\Lambda_v^b = \Lambda_v = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}, \quad (4c)$$

and

$$\bar{\Lambda}_v = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, \quad (4d)$$

hence, the matrices  $\bar{\theta}_{\sim bi}$ ,  $\bar{\theta}_{\sim bv}$  and vector  $\theta_{\sim b}$  of (39) of Part I are simply

$$\bar{\theta}_{\sim bi} = M_{\sim 11}^b, \quad (5a)$$

$$\bar{\theta}_{\sim bv} = M_{\sim 12}^b \quad (5b)$$

and

$$\theta_{\sim b} = \hat{\eta}_{\sim bx}. \quad (5c)$$

Tables I and II show the corresponding matrices  $\bar{\theta}_{\sim bi}$  and  $\bar{\theta}_{\sim bv}$  and vector  $\theta_{\sim b}$  for different power system elements considering the sets of element variables  $\bar{z}_{\sim b}$  and  $\tilde{z}_{\sim b}$ , respectively.

#### IV. POWER SYSTEM ADJOINT ELEMENTS

Using the results outlined in Table I, the equations defining the adjoint elements for the set of element variables  $\bar{z}_{\sim l}$  are, for a load

$$\hat{I}_l = -(S_l/V_l^2) \hat{V}_l^* + [ |V_l| \frac{\partial f}{\partial |V_l|} - j \frac{\partial f}{\partial \delta_l} ] / (2V_l), \quad (6)$$

for a generator

$$V_g \hat{I}_g - V_g^* \hat{I}_g^* = (S_g^*/V_g^*) \hat{V}_g - (S_g/V_g) \hat{V}_g^* - j \frac{\partial f}{\partial \delta_g} \quad (7a)$$

and

$$V_g \hat{V}_g - V_g^* \hat{V}_g^* = -j V_g V_g^* \frac{\partial f}{\partial Q_g}, \quad (7b)$$

where each of (7a) and (7b) represents only one condition, for the slack generator

$$\hat{V}_n = -V_n^* \left( \frac{\partial f}{\partial P_n} + j \frac{\partial f}{\partial Q_n} \right) / 2, \quad (8)$$

and for a transmission element

$$\hat{I}_t = Y_t \hat{V}_t + Y_t \left[ \frac{\partial f}{\partial \text{Re}\{I_t\}} - j \frac{\partial f}{\partial \text{Im}\{I_t\}} \right] / 2. \quad (9)$$

Similarly, using the results outlined in Table II, the equations defining the adjoint elements using the set of element variables  $\tilde{z}_l$  are, for a load

$$\hat{I}_l = - (S_l / V_l^2) \hat{V}_l^* + \frac{\partial f}{\partial V_l}, \quad (10)$$

for a generator

$$V_g \hat{I}_g - V_g^* \hat{I}_g^* = -j 2 Q_g \hat{V}_g^* / V_g + V_g \frac{\partial f}{\partial V_g}, \quad (11a)$$

and

$$V_g \hat{V}_g - V_g^* \hat{V}_g^* = -V_g \frac{\partial f}{\partial I_g}, \quad (11b)$$

where each of (11a) and (11b) represents only one condition, for the slack generator

$$\hat{V}_n = - \frac{\partial f}{\partial I_n} \quad (12)$$

and for a transmission element

$$\hat{I}_t = Y_t \hat{V}_t + Y_t \frac{\partial f}{\partial I_t}. \quad (13)$$



Note incidentally that, for transmission elements, equations (9) and (13) have the form

$$\hat{I}_t = Y_t \hat{V}_t + \hat{I}_t^S. \quad (14)$$

Comparing (53) of Part I and (14), we get

$$\bar{Y}_{t1} = \tilde{Y}_{t1} = Y_{t1} \quad (15a)$$

and

$$\bar{Y}_{t2} = \tilde{Y}_{t2} = Y_{t2}, \quad (15b)$$

where

$$Y_t = Y_{t1} + jY_{t2}, \quad (15c)$$

hence, the line admittances of both original and adjoint systems are the same, and (76) of Part I has the form

$$\underset{\sim}{Y}_T \underset{\sim}{V}_M = -(\underset{\sim}{I}_M + \underset{\sim}{J}_M), \quad (16)$$

where  $\underset{\sim}{Y}_T$  is the symmetrical bus admittance matrix of the original system. Moreover, since the matrices  $\phi_{ij}, \psi_{ij}; i, j = 1, 2$  of (74) of Part I are diagonal matrices, the adjoint matrix of coefficients is of the same sparsity as the Jacobian matrix of the original network.

## V. THE ADJOINT EQUATIONS

We write equation (16) in the form

$$\begin{pmatrix} \underset{\sim}{Y}_{LL} & \underset{\sim}{Y}_{LG} & \underset{\sim}{Y}_{LN} \\ \underset{\sim}{Y}_{GL} & \underset{\sim}{Y}_{GG} & \underset{\sim}{Y}_{GN} \\ \underset{\sim}{Y}_{NL} & \underset{\sim}{Y}_{NG} & \underset{\sim}{Y}_{nn} \end{pmatrix} \begin{pmatrix} \hat{\underset{\sim}{V}}_L \\ \hat{\underset{\sim}{V}}_G \\ \hat{\underset{\sim}{V}}_n \end{pmatrix} = - \begin{pmatrix} \hat{\underset{\sim}{I}}_L + \hat{\underset{\sim}{J}}_L \\ \hat{\underset{\sim}{I}}_G + \hat{\underset{\sim}{J}}_G \\ \hat{\underset{\sim}{I}}_n + \hat{\underset{\sim}{J}}_n \end{pmatrix}, \quad (17)$$

where the  $n \times n$  bus admittance matrix has been partitioned into blocks associated with the sets of load, generator and slack buses of appropriate dimension, and  $\hat{V}_M$ ,  $\hat{I}_M$  and  $\hat{J}_M$  have been partitioned correspondingly.

We also write the diagonal matrices  $\phi_{ij}$  and  $\psi_{ij}$ ;  $i, j = 1, 2$  and the vector  $\hat{W}_M^S$  of (74) of Part I in the corresponding partitioned forms

$$\phi_{ij} = \begin{pmatrix} \phi_{ij}^L & 0 & 0 \\ 0 & \phi_{ij}^G & 0 \\ 0 & 0 & \phi_{ij}^n \end{pmatrix}, \quad (18a)$$

$$\psi_{ij} = \begin{pmatrix} \psi_{ij}^L & 0 & 0 \\ 0 & \psi_{ij}^G & 0 \\ 0 & 0 & \psi_{ij}^n \end{pmatrix}, \quad (18b)$$

where  $\phi_{ij}^L$ ,  $\phi_{ij}^G$ ,  $\psi_{ij}^L$  and  $\psi_{ij}^G$  are diagonal submatrices, and

$$\hat{W}_M^S = \begin{pmatrix} \hat{W}_L^S \\ \hat{W}_G^S \\ \hat{W}_n^S \end{pmatrix}. \quad (18c)$$

Using the forms (17) and (18) it is straight forward to show that the adjoint system of equations (74) of Part I can be written in the form

$$\begin{array}{cccc}
 \phi_{\sim 11}^L G_{\sim LL} + \phi_{\sim 12}^L B_{\sim LL} + \psi_{\sim 11}^L & \phi_{\sim 11}^L G_{\sim LG} + \phi_{\sim 12}^L B_{\sim LG} & -\phi_{\sim 11}^L B_{\sim LL} + \phi_{\sim 12}^L G_{\sim LL} + \psi_{\sim 12}^L & -\phi_{\sim 11}^L B_{\sim LG} + \phi_{\sim 12}^L G_{\sim LG} \\
 \phi_{\sim 11}^G G_{\sim GL} + \phi_{\sim 12}^G B_{\sim GL} & \phi_{\sim 11}^G G_{\sim GG} + \phi_{\sim 12}^G B_{\sim GG} + \psi_{\sim 11}^G & -\phi_{\sim 11}^G B_{\sim GL} + \phi_{\sim 12}^G G_{\sim GL} & -\phi_{\sim 11}^G B_{\sim GG} + \phi_{\sim 12}^G G_{\sim GG} + \psi_{\sim 12}^G \\
 \phi_{\sim 21}^L G_{\sim LL} + \phi_{\sim 22}^L B_{\sim LL} + \psi_{\sim 21}^L & \phi_{\sim 21}^L G_{\sim LG} + \phi_{\sim 22}^L B_{\sim LG} & -\phi_{\sim 21}^L B_{\sim LL} + \phi_{\sim 22}^L G_{\sim LL} + \psi_{\sim 22}^L & -\phi_{\sim 21}^L B_{\sim LG} + \phi_{\sim 22}^L G_{\sim LG} \\
 \phi_{\sim 21}^G G_{\sim GL} + \phi_{\sim 22}^G B_{\sim GL} & \phi_{\sim 21}^G G_{\sim GG} + \phi_{\sim 22}^G B_{\sim GG} + \psi_{\sim 21}^G & -\phi_{\sim 21}^G B_{\sim GL} + \phi_{\sim 22}^G G_{\sim GL} & -\phi_{\sim 21}^G B_{\sim GG} + \phi_{\sim 22}^G G_{\sim GG} + \psi_{\sim 22}^G
 \end{array}$$

$$\begin{array}{c}
 \hat{V}_{\sim L1} \\
 \hat{V}_{\sim G1} \\
 \hat{V}_{\sim L2} \\
 \hat{V}_{\sim G2}
 \end{array}
 = - \begin{array}{c}
 \phi_{\sim 11}^L \hat{J}_{\sim L1} + \phi_{\sim 12}^L \hat{J}_{\sim L2} + \hat{W}_{\sim L1}^S \\
 (\phi_{\sim 11}^L G_{\sim LN} + \phi_{\sim 12}^L B_{\sim LN}) \hat{V}_{n1} - (\phi_{\sim 11}^L B_{\sim LG} - \phi_{\sim 12}^L G_{\sim LG}) \hat{V}_{n2} \\
 \phi_{\sim 11}^G \hat{J}_{\sim G1} + \phi_{\sim 12}^G \hat{J}_{\sim G2} + \hat{W}_{\sim G1}^S \\
 (\phi_{\sim 11}^G G_{\sim GN} + \phi_{\sim 12}^G B_{\sim GN}) \hat{V}_{n1} - (\phi_{\sim 11}^G B_{\sim GN} - \phi_{\sim 12}^G G_{\sim GN}) \hat{V}_{n2} \\
 \phi_{\sim 21}^L \hat{J}_{\sim L1} + \phi_{\sim 22}^L \hat{J}_{\sim L2} + \hat{W}_{\sim L2}^S \\
 (\phi_{\sim 21}^L G_{\sim LN} + \phi_{\sim 22}^L B_{\sim LN}) \hat{V}_{n1} - (\phi_{\sim 21}^L B_{\sim LN} - \phi_{\sim 22}^L G_{\sim LN}) \hat{V}_{n2} \\
 \phi_{\sim 21}^G \hat{J}_{\sim G1} + \phi_{\sim 22}^G \hat{J}_{\sim G2} + \hat{W}_{\sim G2}^S \\
 (\phi_{\sim 21}^G G_{\sim GN} + \phi_{\sim 22}^G B_{\sim GN}) \hat{V}_{n1} - (\phi_{\sim 21}^G B_{\sim GN} - \phi_{\sim 22}^G G_{\sim GN}) \hat{V}_{n2}
 \end{array}
 \tag{19}$$

where

$$Y_{\sim IJ} = G_{\sim IJ} + j B_{\sim IJ}, \tag{20a}$$

$$\hat{V}_{\sim K} = \hat{V}_{\sim K1} + j \hat{V}_{\sim K2}, \tag{20b}$$

$$\hat{J}_{\sim K} = \hat{J}_{\sim K1} + j \hat{J}_{\sim K2}, \tag{20c}$$

$$\hat{W}_K^S = \hat{W}_{K1}^S + j \hat{W}_{K2}^S \quad (20d)$$

and I, J and K can be G, L, N or n.

Note that the form (19) is general for any set of element variables. The adjoint matrix of coefficients has dimension  $2(n-1) \times 2(n-1)$  where the slack bus equations have been omitted.

Tables III and IV show the parameters of the adjoint system (19) for the sets of element variables  $\bar{z}_b$  and  $\tilde{z}_b$ , respectively. For simplicity, only general elements of the diagonal matrices and of the vectors are shown.

The structure of the adjoint system (19) for any of the two cases is simplified to

$$\left( \begin{array}{cccc} \underline{G}_{LL} + \underline{\psi}_{11}^L & \underline{G}_{LG} & -\underline{B}_{LL} + \underline{\psi}_{12}^L & -\underline{B}_{LG} \\ \hline \underline{\phi}_{11}^G \underline{G}_{GL} + \underline{\phi}_{12}^G \underline{B}_{GL} & \underline{\phi}_{11}^G \underline{G}_{GG} + \underline{\phi}_{12}^G \underline{B}_{GG} + \underline{\psi}_{11}^G & -\underline{\phi}_{11}^G \underline{B}_{GL} + \underline{\phi}_{12}^G \underline{G}_{GL} & -\underline{\phi}_{11}^G \underline{B}_{GG} + \underline{\phi}_{12}^G \underline{G}_{GG} + \underline{\psi}_{12}^G \\ \hline \underline{B}_{LL} + \underline{\psi}_{21}^L & \underline{B}_{LG} & \underline{G}_{LL} + \underline{\psi}_{22}^L & \underline{G}_{LG} \\ \hline 0 & \underline{\psi}_{21}^G & 0 & \underline{\psi}_{22}^G \end{array} \right)$$

$$\left( \begin{array}{c} \hat{V}_{L1} \\ \hat{V}_{G1} \\ \hat{V}_{L2} \\ \hat{V}_{G2} \end{array} \right) = - \left( \begin{array}{c} \hat{J}_{L1} + \hat{W}_{L1}^S + \underline{G}_{LN} \hat{V}_{n1} - \underline{B}_{LG} \hat{V}_{n2} \\ \hline \underline{\phi}_{11}^G [\hat{J}_{G1} + \underline{G}_{GN} \hat{V}_{n1} - \underline{B}_{GN} \hat{V}_{n2}] + \underline{\phi}_{12}^G [\hat{J}_{G2} + \underline{B}_{GN} \hat{V}_{n1} + \underline{G}_{GN} \hat{V}_{n2}] + \hat{W}_{G1}^S \\ \hline \hat{J}_{L2} + \hat{W}_{L2}^S + \underline{B}_{LN} \hat{V}_{n1} + \underline{G}_{LN} \hat{V}_{n2} \\ \hline \hat{W}_{G2}^S \end{array} \right) \quad (21)$$

### VI. GRADIENT CALCULATIONS

The derivatives of the function  $f$  w.r.t. the control variables are calculated from

$$\frac{df}{du_b} = \frac{\partial f}{\partial u_b} - \hat{\eta}_{bu} \quad (22)$$

or

$$\frac{df}{\partial \tau_{bi}} = \left[ \left( \frac{\partial f}{\partial u_b} \right)^T - \hat{\eta}_{bu}^T \right] \frac{\partial u_b}{\partial \tau_{bi}}, \quad (23)$$

derived in Part I. The vector  $\hat{\eta}_{bu}$  is obtained from (32) of Part I, namely

$$\hat{\eta}_{bu} = M_{21}^b \hat{f}_{bi} + M_{22}^b \hat{f}_{bv}, \quad (24)$$

where the vector  $\hat{f}_b$  is given, for the considered case, by

$$\hat{f}_b = \begin{bmatrix} \hat{f}_{bi} \\ \hat{f}_{bv} \end{bmatrix} = \begin{bmatrix} \hat{I}_b \\ \hat{I}_b^* \\ -\hat{V}_b \\ -\hat{V}_b^* \end{bmatrix}, \quad (25)$$

and the matrices  $M_{21}^b$  and  $M_{22}^b$  are given in Tables III and IV of Part I.

Tables V and VI show the vector  $\hat{\eta}_{bu}$  for different power system elements in the special considered case using the sets of element variables  $\bar{z}_b$  and  $\bar{z}_b^*$ , respectively.

## VII. EXAMPLES

In this section, we present some numerical results to illustrate the use of the derived formulas. A 6-bus sample power system [3,6] shown in Fig. 1 is considered.

Required data for the problem is shown in Tables VII and VIII. Powers injected into buses are shown. The corresponding a.c. load flow solution is shown in Table IX. Tables X and XI show the coefficient matrices of the adjoint systems corresponding to element variables  $\bar{z}_b$  and  $\tilde{z}_b$ , respectively. These matrices are common to all the sensitivity calculations.

So as not to be restricted to any particular application, we consider the following examples where we consider, without loss of generality, the sensitivities of some system states and a function representing the total transmission losses in the system. The control variables associated with the transmission elements are taken as the line conductances  $G_t$  and susceptances  $B_t$ .

The results presented have been checked by small perturbations about the base point.

### Example 1

In this example, we consider the states associated with the load bus number 3. Element variables  $\bar{z}_b$  are used. Table XII shows the RHS vector of the adjoint equations for both states and the adjoint voltages resulting from the solution of (21). Table XIII shows the derivatives calculated by our approach.

Example 2

Now, we consider the states associated with the generator bus number 5. Element variables  $\bar{z}_b$  are used. The RHS vector of the adjoint equations for both states and the adjoint voltages resulting from the solution of (21) are shown in Table XIV. Table XVa shows the derivatives calculated by our approach.

Using element variables  $\bar{z}_b$ , the derivatives w.r.t.  $S_\ell$ , for example, are shown in Table XVb. Note that from (3) of Part I

$$\frac{\partial f}{\partial S_\ell^*} = \left( \frac{\partial f}{\partial S_\ell} \right)^*$$

Example 3

In this example, we consider the function

$$f = \sum_t |I_t|^2 R_t,$$

which represents the total transmission losses in the power network.

Table XVI shows the RHS vector of the adjoint equations for this function and the adjoint voltages resulting from the solution of (21). Table XVII shows the derivatives calculated by our approach. Element variables  $\bar{z}_b$  are used.

Example 4

In this example, we investigate line removals by considering functions of the form

$$f = |I_t|^2.$$

The control variables associated with generator and load buses are maintained at their base-case values.

Table XVIII shows some results of different contingencies.

### VIII. CONCLUSIONS

We have considered a class of adjoint systems in which the extended Tellegen sum (introduced in Part I) is a real quantity. A detailed discussion of an important case in which the selection of the adjoining complex coefficients lead to an adjoint system of a special structure has been presented. The adjoint matrix of coefficients is of the same size and sparsity as the Jacobian matrix of the load flow equations of the original power network.

Sensitivity expressions have been presented and adjoint elements have been defined permitting a wide variety of problems to be handled. A number of relevant problems have been numerically explored for a 6-bus sample power system. The application of the formulas, which have been derived for two important sets of variables, has been illustrated.



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TABLE Ia

ELEMENTS OF  $\bar{\theta}_{bi}$ ,  $\bar{\theta}_{bv}$  AND  $\theta_b$  USING ELEMENT VARIABLES  $\bar{z}_b$

	Load Elements	Generator Elements
$\bar{\theta}_{bi}$	$\begin{bmatrix} V_l /  V_l  & V_l^* /  V_l  \\ jV_l & -jV_l^* \end{bmatrix}$	$\begin{bmatrix} jV_g & -jV_g^* \\ 0 & 0 \end{bmatrix}$
$\bar{\theta}_{bv}$	$\begin{bmatrix} -S_l^* / (V_l^*  V_l ) & -S_l / (V_l  V_l ) \\ jS_l^* / V_l^* & -jS_l / V_l \end{bmatrix}$	$\begin{bmatrix} jS_g^* / V_g^* & -jS_g / V_g \\ -j / V_g^* & j / V_g \end{bmatrix}$
$\theta_b$	$\begin{bmatrix} \frac{\partial f}{\partial  V_l } \\ \frac{\partial f}{\partial \delta_l} \end{bmatrix}$	$\begin{bmatrix} \frac{\partial f}{\partial \delta_g} \\ \frac{\partial f}{\partial Q_g} \end{bmatrix}$

TABLE Ib

ELEMENTS OF  $\bar{\theta}_{bi}$ ,  $\bar{\theta}_{bv}$  AND  $\theta_b$  USING ELEMENT VARIABLES  $\bar{z}_b$

	Slack Generator	Transmission Elements
$\bar{\theta}_{bi}$	$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 1/Y_t & 1/Y_t^* \\ j/Y_t & -j/Y_t^* \end{pmatrix}$
$\bar{\theta}_{bv}$	$\begin{pmatrix} 1/V_n^* & 1/V_n \\ -j/V_n^* & j/V_n \end{pmatrix}$	$\begin{pmatrix} 1 & 1 \\ j & -j \end{pmatrix}$
$\theta_b$	$\begin{pmatrix} \frac{\partial f}{\partial P_n} \\ \frac{\partial f}{\partial Q_n} \end{pmatrix}$	$\begin{pmatrix} \frac{\partial f}{\partial \text{Re}\{I_t\}} \\ \frac{\partial f}{\partial \text{Im}\{I_t\}} \end{pmatrix}$

TABLE II

ELEMENTS OF  $\bar{\theta}_{bi}$ ,  $\bar{\theta}_{bv}$  and  $\theta_b$  USING ELEMENT VARIABLES  $\tilde{z}_b$

	Load Elements	Generator Elements	Slack Generator	Transmission Elements
$\bar{\theta}_{bi}$	$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & -V_g^*/V_g \\ 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 1/Y_t & 0 \\ 0 & 1/Y_t^* \end{pmatrix}$
$\bar{\theta}_{bv}$	$\begin{pmatrix} 0 & -S_l/V_l^2 \\ -S_l^*/V_l^{*2} & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & -j2Q_g/V_g^2 \\ 1 & -V_g^*/V_g \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$
$\theta_b$	$\begin{pmatrix} \frac{\partial f}{\partial V_l} \\ \frac{\partial f}{\partial V_l^*} \end{pmatrix}$	$\begin{pmatrix} \frac{\partial f}{\partial V_g} \\ \frac{\partial f}{\partial I_g} \end{pmatrix}$	$\begin{pmatrix} \frac{\partial f}{\partial I_n} \\ \frac{\partial f}{\partial I_n^*} \end{pmatrix}$	$\begin{pmatrix} \frac{\partial f}{\partial I_t} \\ \frac{\partial f}{\partial I_t^*} \end{pmatrix}$

TABLE III  
PARAMETERS OF ADJOINT SYSTEM USING ELEMENT VARIABLES  $\bar{z}_b$

Load Elements

$$\begin{aligned} \phi_{11}^l &= 1 & \psi_{11}^l &= \operatorname{Re}\{-S_l/V_l^2\} & \hat{W}_{l1}^S &= \operatorname{Re}\left\{\left(|V_l| \frac{\partial f}{\partial |V_l|} - j \frac{\partial f}{\partial \delta_l}\right) / (2V_l)\right\} \\ \phi_{12}^l &= 0 & \psi_{12}^l &= \operatorname{Im}\{-S_l/V_l^2\} \\ \phi_{21}^l &= 0 & \psi_{21}^l &= \operatorname{Im}\{-S_l/V_l^2\} & \hat{W}_{l2}^S &= \operatorname{Im}\left\{\left(|V_l| \frac{\partial f}{\partial |V_l|} - j \frac{\partial f}{\partial \delta_l}\right) / (2V_l)\right\} \\ \phi_{22}^l &= 1 & \psi_{22}^l &= \operatorname{Re}\{S_l/V_l^2\} \end{aligned}$$

Generator Elements

$$\begin{aligned} \phi_{11}^g &= 2\operatorname{Im}\{V_g\} & \psi_{11}^g &= -2\operatorname{Im}\{S_g/V_g\} & \hat{W}_{g1}^S &= -\frac{\partial f}{\partial \delta_g} \\ \phi_{12}^g &= 2\operatorname{Re}\{V_g\} & \psi_{12}^g &= 2\operatorname{Re}\{S_g/V_g\} \\ \phi_{21}^g &= 0 & \psi_{21}^g &= 2\operatorname{Im}\{V_g\} & \hat{W}_{g2}^S &= |V_g|^2 \frac{\partial f}{\partial Q_g} \\ \phi_{22}^g &= 0 & \psi_{22}^g &= 2\operatorname{Re}\{V_g\} \end{aligned}$$

Slack Generator

$$\hat{V}_n = -V_n^* \left( \frac{\partial f}{\partial P_n} + j \frac{\partial f}{\partial Q_n} \right) / 2$$

Transmission Elements

$$\begin{aligned} \hat{I}_t^S &= Y_t \left( \frac{\partial f}{\partial \operatorname{Re}\{I_t\}} - j \frac{\partial f}{\partial \operatorname{Im}\{I_t\}} \right) / 2, \text{ hence } \hat{J}_{m1} = \sum_t a_{mt} \operatorname{Re}\{\hat{I}_t^S\} \text{ and} \\ \hat{J}_{m2} &= \sum_t a_{mt} \operatorname{Im}\{\hat{I}_t^S\}; m = l \text{ or } g. \end{aligned}$$

The  $a_{mt}$  are elements of the reduced incidence matrix (68) of Part I.

TABLE IV  
PARAMETERS OF ADJOINT SYSTEM USING ELEMENT VARIABLES  $\tilde{z}_b$

Load Elements

$\phi_{11}^l = 1$	$\psi_{11}^l = \text{Re}\{-S_l/V_l^2\}$	$\hat{W}_{l1}^S = \text{Re}\left\{\frac{\partial f}{\partial V_l}\right\}$
$\phi_{12}^l = 0$	$\psi_{12}^l = \text{Im}\{-S_l/V_l^2\}$	
$\phi_{21}^l = 0$	$\psi_{21}^l = \text{Im}\{-S_l/V_l^2\}$	$\hat{W}_{l2}^S = \text{Im}\left\{\frac{\partial f}{\partial V_l}\right\}$
$\phi_{22}^l = 1$	$\psi_{22}^l = \text{Re}\{S_l/V_l^2\}$	

Generator Elements

$\phi_{11}^g = 2\text{Im}\{V_g\}$	$\psi_{11}^g = \text{Im}\{-j2Q_g/V_g\}$	$\hat{W}_{g1}^S = \text{Im}\left\{V_g \frac{\partial f}{\partial V_g}\right\}$
$\phi_{12}^g = 2\text{Re}\{V_g\}$	$\psi_{12}^g = \text{Re}\{j2Q_g/V_g\}$	
$\phi_{21}^g = 0$	$\psi_{21}^g = 2\text{Im}\{V_g\}$	$\hat{W}_{g2}^S = \text{Im}\left\{V_g \frac{\partial f}{\partial I_g}\right\}$
$\phi_{22}^g = 0$	$\psi_{22}^g = 2\text{Re}\{V_g\}$	

Slack Generator

$$\hat{V}_n = -\frac{\partial f}{\partial I_n}$$

Transmission Elements

$$\hat{I}_t^S = Y_t \frac{\partial f}{\partial I_t}, \text{ hence } \hat{J}_{m1} = \sum_t a_{mt} \text{Re}\{\hat{I}_t^S\} \text{ and } \hat{J}_{m2} = \sum_t a_{mt} \text{Im}\{\hat{I}_t^S\}; m = l \text{ or } g.$$

The  $a_{mt}$  are elements of the reduced incidence matrix (68) of Part I.

TABLE Va

THE VECTOR  $\hat{\underline{n}}_{bu}$  USING ELEMENT VARIABLES  $\bar{\underline{z}}_b$

	Load Elements	Generator Elements
$\hat{\underline{n}}_{bu}$	$\begin{bmatrix} -\hat{V}_l/V_l^* - \hat{V}_l^*/V_l \\ j\hat{V}_l/V_l^* - j\hat{V}_l^*/V_l \end{bmatrix}$	$\begin{bmatrix} [V_g \hat{I}_g + V_g^* \hat{I}_g^* + S_g \hat{V}_g/V_g^* + S_g \hat{V}_g^*/V_g] /  V_g  \\ -\hat{V}_g/V_g^* - \hat{V}_g^*/V_g \end{bmatrix}$

TABLE Vb

THE VECTOR  $\hat{\underline{n}}_{bu}$  USING ELEMENT VARIABLES  $\bar{\underline{z}}_b$

	Slack Generator	Transmission Elements
$\hat{\underline{n}}_{bu}$	$\begin{bmatrix} [V_n \hat{I}_n + V_n^* \hat{I}_n^* + S_n \hat{V}_n/V_n^* + S_n \hat{V}_n^*/V_n]  V_n  \\ j[V_n \hat{I}_n - V_n^* \hat{I}_n^* - S_n \hat{V}_n/V_n^* + S_n \hat{V}_n^*/V_n] \end{bmatrix}$	$\begin{bmatrix} -V_t \hat{I}_t/Y_t - V_t^* \hat{I}_t^*/Y_t^* \\ j[-V_t \hat{I}_t/Y_t + V_t^* \hat{I}_t^*/Y_t^*] \end{bmatrix}$

TABLE VI  
THE VECTOR  $\hat{\eta}_{bu}$  USING ELEMENT VARIABLES  $\tilde{z}_b$

	Load Elements	Generator Elements	Slack Generator	Transmission Elements
$\hat{\eta}_{bu}$	$\begin{pmatrix} -\hat{V}_l^*/V_l \\ -\hat{V}_l^*/V_l^* \end{pmatrix}$	$\begin{pmatrix} \hat{I}_g^*/V_g + S_g^*\hat{V}_g^*/V_g^*V_g^2 \\ -\hat{V}_g^*/V_g \end{pmatrix}$	$\begin{pmatrix} \hat{I}_n \\ \hat{I}_n^* \end{pmatrix}$	$\begin{pmatrix} V_t \hat{I}_t/Y_t \\ V_t^* \hat{I}_t^*/Y_t^* \end{pmatrix}$

TABLE VII

BUS DATA

Bus Index, i	Bus Type	$P_i$ (pu)	$Q_i$ (pu)	$ V_i  \angle \delta_i$ (pu)
1	load	-2.40	0	- $\angle$ -
2	load	-2.40	0	- $\angle$ -
3	load	-1.60	-0.40	- $\angle$ -
4	generator	-0.30	-	1.02 $\angle$ -
5	generator	1.25	-	1.04 $\angle$ -
6	slack	-	-	1.04 $\angle$ 0



TABLE VIII

LINE DATA

Branch Index, $t$	Terminal Buses	Resistance $R_t$ (pu)	Reactance $X_t$ (pu)	Number of Lines
7	1,4	0.05	0.20	1
8	1,5	0.025	0.10	2
9	2,3	0.10	0.40	1
10	2,4	0.10	0.40	1
11	2,5	0.05	0.20	1
12	2,6	0.01875	0.075	4
13	3,4	0.15	0.60	1
14	3,6	0.0375	0.15	2

TABLE IX

LOAD FLOW SOLUTION

Load Buses

$$V_1 = 0.9787 \angle -0.6602$$

$$V_2 = 0.9633 \angle -0.2978$$

$$V_3 = 0.9032 \angle -0.3036$$

Generator Buses

$$Q_4 = 0.7866; \quad \delta_4 = -0.5566$$

$$Q_5 = 0.9780; \quad \delta_5 = -0.4740$$

Slack Bus

$$P_6 = 6.1298; \quad Q_6 = 1.3546$$

TABLE X  
ADJOINT MATRIX OF COEFFICIENTS USING ELEMENT VARIABLES  $\bar{z}_b$

2.9085	0	0	- 1.1765	- 2.3529	11.6900	0	0	-4.7059	-9.4118
0	3.3490	- 0.5882	- 0.5882	- 1.1765	0	20.5097	-2.3529	-2.3529	-4.7059
0	- 0.5882	1.2179	- 0.3922	0	0	- 2.3529	8.6744	-1.5686	0
9.4189	4.7095	3.1396	-16.2693	0	3.0338	1.5169	1.0113	-4.2477	0
19.6518	9.8259	0	0	-26.7071	4.5821	2.2910	0	0	-8.1534
-16.5453	0	0	4.7059	9.4118	4.1503	0	0	-1.1765	-2.3529
0	-23.4119	2.3529	2.3529	4.7059	0	7.6314	-0.5882	-0.5882	-1.1765
0	2.3529	-11.7178	1.5686	0	0	- 0.5882	3.8802	-0.3922	0
0	0	0	- 1.0777	0	0	0	0	1.7321	0
0	0	0	0	- 0.9495	0	0	0	0	1.8506

TABLE XI  
 ADJOINT MATRIX OF COEFFICIENTS USING ELEMENT VARIABLES  $\tilde{z}_b$

2.9085	0	0	- 1.1765	- 2.3529	11.6900	0	0	-4.7059	-9.4118
0	3.3490	- 0.5882	- 0.5882	- 1.1765	0	20.5097	-2.3529	-2.3529	-4.7059
0	- 0.5882	1.2179	- 0.3922	0	0	- 2.3529	8.6744	-1.5686	0
9.4189	4.7095	3.1396	-15.9585	0	3.0338	1.5169	1.0113	-4.7471	0
19.6519	9.8259	0	0	-27.8045	4.5821	2.2910	0	0	-6.0146
-16.5453	0	0	4.7059	9.4118	4.1503	0	0	-1.1765	-2.3529
0	-23.4119	2.3529	2.3529	4.7059	0	7.6314	-0.5882	-0.5882	-1.1765
0	2.3529	-11.7178	1.5686	0	0	- 0.5882	3.8802	-0.3922	0
0	0	0	- 1.0777	0	0	0	0	1.7321	0
0	0	0	0	- 0.9495	0	0	0	0	1.8506

TABLE XII

RHS AND SOLUTION VECTORS OF THE ADJOINT NETWORKS FOR THE STATES OF BUS 3

Element No.	$f =  v_3 $		$f = \delta_3$	
	RHS Vector	Solution Vector	RHS Vector	Solution Vector
1	0	$-0.1016 \times 10^{-1}$	0	$-0.2232 \times 10^{-1}$
2	0	$-0.5260 \times 10^{-2}$	0	$-0.1421 \times 10^{-1}$
3	-0.4771	$-0.8741 \times 10^{-2}$	-0.1655	$-0.5699 \times 10^{-1}$
4	0	$-0.1301 \times 10^{-1}$	0	$-0.2867 \times 10^{-1}$
5	0	$-0.1003 \times 10^{-1}$	0	$-0.2200 \times 10^{-1}$
6	0	$-0.8205 \times 10^{-2}$	0	$-0.1803 \times 10^{-1}$
7	0	$-0.9182 \times 10^{-2}$	0	$-0.8189 \times 10^{-2}$
8	-0.1495	$-0.5868 \times 10^{-1}$	0.5283	$-0.1878 \times 10^{-1}$
9	0	$-0.8095 \times 10^{-2}$	0	$-0.1784 \times 10^{-1}$
10	0	$-0.5148 \times 10^{-2}$	0	$-0.1129 \times 10^{-1}$

TABLE XIII  
RESULTS OF EXAMPLE 1

Line Quantities

Line	Derivatives w.r.t. $G_t$		Derivatives w.r.t. $B_t$	
	$f =  V_3 $	$f = \delta_3$	$f =  V_3 $	$f = \delta_3$
1,4	$-0.5441 \times 10^{-3}$	$-0.1205 \times 10^{-2}$	$0.3294 \times 10^{-3}$	$0.7433 \times 10^{-3}$
1,5	$-0.7289 \times 10^{-3}$	$-0.1595 \times 10^{-2}$	$-0.9625 \times 10^{-3}$	$-0.2133 \times 10^{-2}$
2,3	$0.1664 \times 10^{-2}$	$0.5312 \times 10^{-2}$	$-0.5748 \times 10^{-2}$	$-0.1659 \times 10^{-3}$
2,4	$0.1407 \times 10^{-2}$	$-0.3359 \times 10^{-2}$	$-0.3853 \times 10^{-2}$	$-0.8465 \times 10^{-2}$
2,5	$0.1507 \times 10^{-2}$	$-0.1260 \times 10^{-2}$	$-0.1870 \times 10^{-2}$	$-0.2965 \times 10^{-2}$
2,6	0.2439	0.2466	-0.5931	-0.5979
3,4	$0.2716 \times 10^{-1}$	$0.7436 \times 10^{-3}$	$-0.2716 \times 10^{-2}$	$0.1522 \times 10^{-1}$
3,6	0.3419	0.3806	-0.5872	-0.5990

Load Bus Quantities

Bus	Derivatives w.r.t. $P_l$		Derivatives w.r.t. $Q_l$	
	$f =  V_3 $	$f = \delta_3$	$f =  V_3 $	$f = \delta_3$
1	$0.2668 \times 10^{-1}$	$0.5862 \times 10^{-1}$	$0.5125 \times 10^{-3}$	$0.1132 \times 10^{-2}$
2	$0.1603 \times 10^{-1}$	$0.3320 \times 10^{-1}$	$0.1502 \times 10^{-1}$	$0.7596 \times 10^{-2}$
3	$0.5731 \times 10^{-1}$	0.1329	0.1182	$0.1969 \times 10^{-2}$

Generator Bus Quantities

Bus	Derivatives w.r.t. $ V_g $		Derivatives w.r.t. $P_g$	
	$f =  V_3 $	$f = \delta_3$	$f =  V_3 $	$f = \delta_3$
4	0.1948	$-0.8082 \times 10^{-2}$	$0.3005 \times 10^{-1}$	$0.6620 \times 10^{-1}$
5	$0.7978 \times 10^{-1}$	$0.5671 \times 10^{-1}$	$0.2169 \times 10^{-1}$	$0.4755 \times 10^{-1}$

TABLE XIV  
 RHS AND SOLUTION VECTORS OF THE ADJOINT NETWORKS  
 FOR THE STATES OF BUS 5

Element No.	$f = \delta_5$		$f = Q_5$	
	RHS Vector	Solution Vector	RHS Vector	Solution Vector
1	0	$-0.9467 \times 10^{-1}$	0	$0.6004 \times 10^{-1}$
2	0	$-0.3649 \times 10^{-1}$	0	$0.2754 \times 10^{-1}$
3	0	$-0.2049 \times 10^{-1}$	0	$0.3282 \times 10^{-1}$
4	0	$-0.7454 \times 10^{-1}$	0	0.1354
5	1.0	-0.1171	0	$-0.2398 \times 10^{-1}$
6	0	$-0.7455 \times 10^{-1}$	0	0.4884
7	0	$-0.2466 \times 10^{-1}$	0	0.1466
8	0	$-0.1804 \times 10^{-1}$	0	$0.5839 \times 10^{-1}$
9	0	$-0.4638 \times 10^{-1}$	0	$0.8427 \times 10^{-1}$
10	0	$-0.6008 \times 10^{-1}$	1.0816	0.5721

TABLE XVa  
RESULTS OF EXAMPLE 2

Line Quantities				
Line	Derivatives w.r.t. $G_t$		Derivatives w.r.t. $B_t$	
	$f = \delta_5$	$f = Q_5$	$f = \delta_5$	$f = Q_5$
	1,4	$0.2892 \times 10^{-3}$	$0.6361 \times 10^{-1}$	$-0.7712 \times 10^{-2}$
1,5	$-0.1046 \times 10^{-1}$	$-0.4660 \times 10^{-1}$	$0.1216 \times 10^{-2}$	$-0.4421 \times 10^{-2}$
2,3	$-0.2054 \times 10^{-2}$	$0.1612 \times 10^{-2}$	$0.3751 \times 10^{-3}$	$-0.1053 \times 10^{-1}$
2,4	$-0.6958 \times 10^{-2}$	$-0.4376 \times 10^{-1}$	$-0.2188 \times 10^{-1}$	$0.4846 \times 10^{-1}$
2,5	$-0.1433 \times 10^{-1}$	0.1630	$-0.3065 \times 10^{-1}$	$-0.2359 \times 10^{-1}$
2,6	0.2426	0.3241	-0.6144	-0.5374
3,4	$-0.1569 \times 10^{-1}$	$0.1477 \times 10^{-1}$	$-0.2883 \times 10^{-1}$	$0.5497 \times 10^{-1}$
3,6	0.3680	0.3903	-0.5790	-0.5230

Load Bus Quantities				
Bus	Derivatives w.r.t. $P_l$		Derivatives w.r.t. $Q_l$	
	$f = \delta_5$	$f = Q_5$	$f = \delta_5$	$f = Q_5$
	1	0.2462	-0.7091	$0.1696 \times 10^{-2}$
2	$0.8745 \times 10^{-1}$	-0.1440	$0.2672 \times 10^{-1}$	-0.2742
3	$0.5524 \times 10^{-1}$	-0.1080	$0.2456 \times 10^{-1}$	-0.1017

Generator Bus Quantities				
Bus	Derivatives w.r.t. $ V_g $		Derivatives w.r.t. $P_g$	
	$f = \delta_5$	$f = Q_5$	$f = \delta_5$	$f = Q_5$
	4	0.1736	-4.5187	0.1721
5	$-0.8889 \times 10^{-1}$	7.5809	0.2531	-0.4612

TABLE XVb  
RESULTS OF EXAMPLE 2

Bus	Derivatives w.r.t. $S_\ell$			
	$f = \delta_5$		$f = Q_5$	
1	0.1231	$-j0.8481 \times 10^{-3}$	-0.3545	$+j0.3566$
2	$0.4372 \times 10^{-1}$	$-j0.1336 \times 10^{-1}$	$-0.7199 \times 10^{-1}$	$+j0.1371$
3	$0.2762 \times 10^{-1}$	$-j0.1228 \times 10^{-1}$	$-0.5400 \times 10^{-1}$	$+j0.5083 \times 10^{-1}$

TABLE XVI  
RHS AND SOLUTION VECTORS OF THE ADJOINT  
NETWORK OF EXAMPLE 3

Element No.	RHS Vector	Solution Vector
1	0.4678	0.1692
2	0.3121	0.0852
3	0.3157	0.0828
4	-0.2337	0.1627
5	0.4732	0.1447
6	-0.3673	0.1440
7	-0.5174	0.0534
8	-0.3106	0.0707
9	0	0.1013
10	0	0.0743



TABLE XVII  
RESULTS OF EXAMPLE 3

Line Quantities

Line	Derivatives w.r.t. $G_t$	Derivatives w.r.t. $B_t$
1,4	$0.1646 \times 10^{-1}$	$0.8741 \times 10^{-2}$
1,5	$0.4900 \times 10^{-1}$	$0.2737 \times 10^{-1}$
2,3	$0.3490 \times 10^{-2}$	$0.2102 \times 10^{-2}$
2,4	$0.8466 \times 10^{-1}$	$0.4496 \times 10^{-1}$
2,5	$0.4547 \times 10^{-1}$	$0.2268 \times 10^{-1}$
2,6	0.3518	-0.5270
3,4	$0.8940 \times 10^{-1}$	$0.4276 \times 10^{-1}$
3,6	0.4838	-0.4917

Load Bus Quantities

Bus	Derivatives w.r.t. $P_\ell$	Derivatives w.r.t. $Q_\ell$
1	-0.4535	$-0.2039 \times 10^{-1}$
2	-0.2017	$-0.5410 \times 10^{-1}$
3	-0.2217	$-0.9465 \times 10^{-1}$

Generator Bus Quantities

Bus	Derivatives w.r.t. $V_g$	Derivatives w.r.t. $P_g$
4	$-0.3736 \times 10^{-1}$	-0.3758
5	-0.1840	-0.3128

TABLE XVIII  
CONTINGENCY RESULTS OF EXAMPLE 4

Function Line Index	Removed Line Index	Calculated Function Change	Exact Function Change
1,4	2,4	-0.200	-0.224
2,3	1,5*	0.002	0.005
2,3	2,3	-0.029	-0.021
2,4	2,4	-0.470	-0.404

\* Only one line of branch 1,5 is removed.

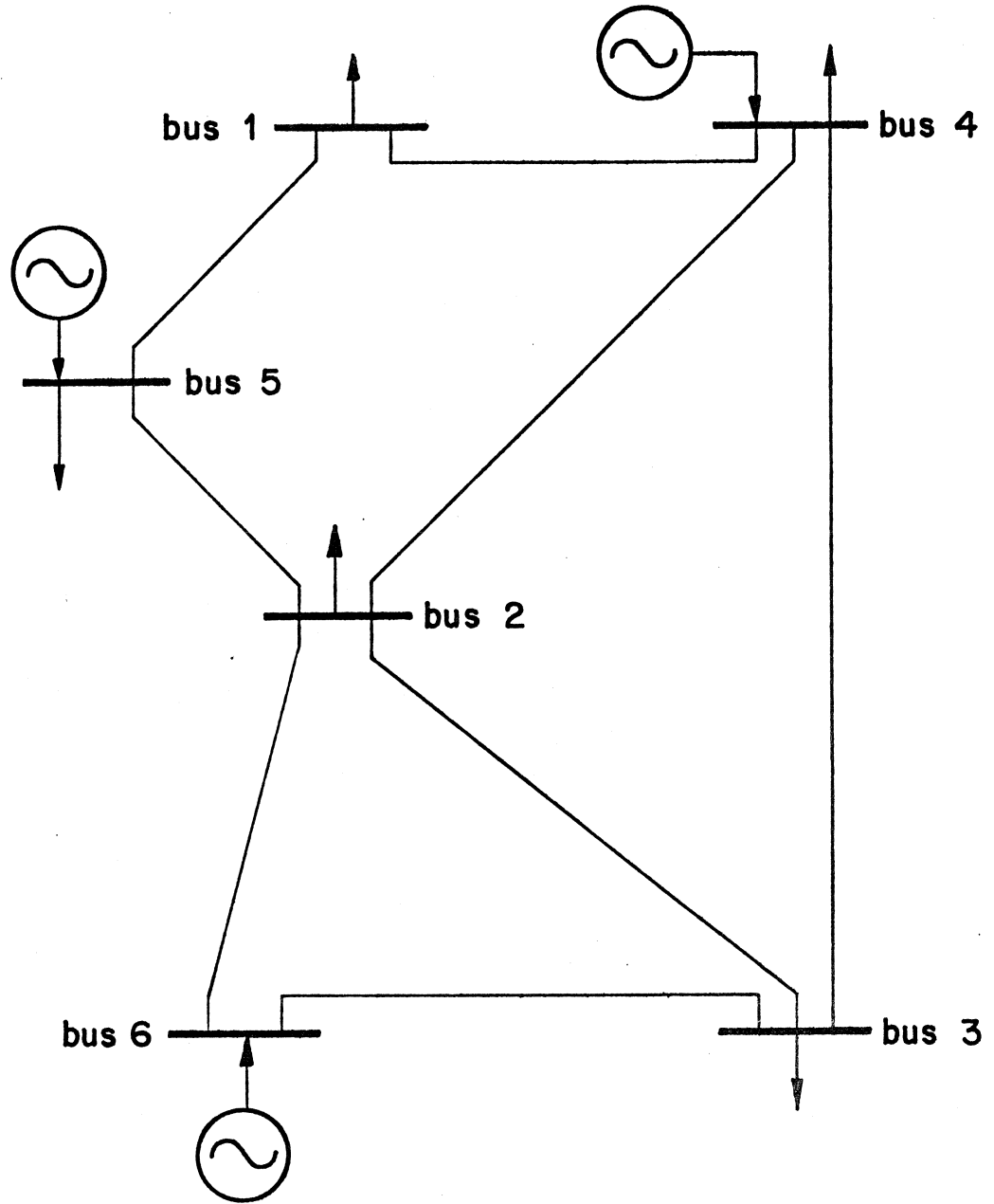


Fig. 1 6-bus sample power system



SOC-238

A UNIFIED APPROACH TO POWER SYSTEM SENSITIVITY ANALYSIS AND PLANNING  
PART II: SPECIAL CLASS OF ADJOINT SYSTEMS

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Key Words: Power system analysis, adjoint networks, Tellegen's theorem, sensitivity analysis, optimal load flows, contingency analysis

Abstract: A unified approach to power system sensitivity analysis and planning has been presented in a companion paper, where a family of adjoint systems based on the exact a.c. power flow model was described. Here, we consider a class of this family in which the extended Tellegen sum is a real quantity. An important practical case is discussed in which the adjoining complex coefficients are set to particular values, which result in an adjoint system of a special structure. The adjoint matrix of coefficients is shown to be of the same size and sparsity as the Jacobian matrix of the original power network. The required sensitivity expressions are derived and tabulated for direct use in sensitivity analysis and gradient evaluation and are common to all relevant power system studies. Numerical examples are presented based on a 6-bus sample power system.

Description:

Related Work: SOC-234, SOC-237.

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